

Improving double protected estimation in causal inference models with longitudinal data.

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Topics

- Double protected estimation.
- Longitudinal data - Causal Analysis.
- Marginal structural mean model.

Double protected estimation in missing data.

Robins JM, Rotnitzky A, Scharfstein D. (1999)

Missing data:

- $Y_i \in \mathbb{R}$ scalar outcome of interest.
- $A_i \in \{0, 1\}$, $A_i = 1$ if Y_i is observed and $A_i = 0$ otherwise.
- $L_i \in \mathbb{R}^m$ vector of additional variables.
- Observed data O_1, \dots, O_n i.i.d., where

$$O_i = \begin{cases} L_i, Y_i, A_i & \text{if } A_i = 1 \\ L_i, A_i & \text{if } A_i = 0. \end{cases}$$

Aim: estimation of the unknown parameter $\beta_0 \in \mathbb{R}$

$$E[Y] = \beta_0.$$

Assumptions: Missing at Random (MAR)

Y is independent of A , given L .

Identifiability :

- MAR guarantees that

$$\beta_0 = E[Y] = E \left[\frac{A}{P(A=1|L)} Y \right].$$

$\hat{\beta}_{\text{ipw}}$ estimator.

Missingness model: (MM)

$$P(A = 1|L) = f(L, \gamma_0). \quad (1)$$

We have that under MM:

$$E \left[\frac{A}{f(L, \gamma_0)} (Y - \beta_0) \right] = 0. \quad (2)$$

Inverse probability weighted estimator (ipw): $\hat{\beta}_{\text{ipw}}$ solves

$$E_n \left[\frac{A}{f(L, \hat{\gamma})} (Y - \beta) \right] = 0, \quad (3)$$

where $\hat{\gamma}$ is the maximum likelihood estimator for γ_0 under MM.

$\hat{\beta}_{\tau, \text{ipw}}$ estimator.

For all measurable functions τ we have:

$$E [\tau(A, L) - E_{\gamma_0}[\tau(A, L)|L]] = 0. \quad (4)$$

Augmented inverse probability weighted estimator: $\hat{\beta}_{\tau, \text{ipw}}$ solves

$$E_n \left[\frac{A}{f(L, \hat{\gamma})} (Y - \beta) \right] - E_n [\tau(A, L) - E_{\hat{\gamma}}[\tau(A, L)|L]] = 0. \quad (5)$$

Local efficiency:

$$\tau_0(A, L) = \frac{A}{f(L, \gamma_0)} \{E[Y|A = 1, L] - \beta_0\},$$

is the function that yields the estimator $\hat{\beta}_{\tau, \text{ipw}}$ with smallest asymptotic variance.

$$E_n\left[\frac{A}{f(L, \hat{\gamma})}(Y - \beta)\right] - E_n\left[\tau(A, L) - E_{\hat{\gamma}}[\tau(A, L)|L]\right] = 0, \quad (6)$$

$$\tau_0(A, L) = \frac{A}{f(L, \gamma_0)}\{E[Y|A = 1, L] - \beta_0\}, \quad (7)$$

$$E[Y|L, A = 1] = m(L, \eta_0), \quad P(A = 1|L) = f(L, \gamma_0), \quad (8)$$

$$\tau_0(A, L) - E_{\gamma_0}[\tau_0(A, L)|L] = \left(\frac{A}{f(L, \gamma_0)} - 1\right)\{m(L, \eta_0) - \beta_0\}, \quad (9)$$

$$\tilde{\tau}_0(A, L) - E_{\hat{\gamma}}[\tilde{\tau}_0(A, L)|L] = \left(\frac{A}{f(L, \hat{\gamma})} - 1\right)\{m(L, \hat{\eta}) - \beta_0\}. \quad (10)$$

Double protected estimator: $\hat{\beta}_{dp}(\hat{\eta}, \hat{\gamma})$ solves

$$E_n \left[\frac{A}{f(L, \hat{\gamma})} (Y - \beta) + \left(1 - \frac{A}{f(L, \hat{\gamma})}\right) \{m(L, \hat{\eta}) - \beta\} \right] = 0, \quad (11)$$

where

- $\hat{\eta}$ is an estimator of η_0 under OR model:

$$E[Y|L, A = 1] = m(L, \eta_0). \quad (12)$$

- $\hat{\gamma}$ is the ml estimator of γ_0 under M model:

$$P(A = 1|L) = f(L, \gamma_0). \quad (13)$$

Theorem

- if $P(A = 1|L) = f(L, \gamma_0)$ and $E[Y|l, A = 1] = m(L, \eta_0)$ then, $\hat{\beta}_{dp}(\hat{\eta}, \hat{\gamma})$ is consistent and asymptotically normal (can) and has asymptotic variance equal to the smallest asymptotic variance of all estimators $\hat{\beta}_{\tau, ipw}$.
- if $P(A = 1|L) = f(L, \gamma_0)$ or $E[Y|L, A = 1] = m(L, \eta_0)$ then, $\hat{\beta}_{dp}(\hat{\eta}, \hat{\gamma})$ is can for β_0 (**doble protected estimator**).

Improving $\hat{\beta}_{dp}(\hat{\eta}, \hat{\gamma})$

Rotnitzky, Lei, Sued and Robins (2009), TAN, Z. (2008), Cao, W., TSIATIS, A. & DAVIDIAN, M. (2009), constructed estimators $\hat{\beta}_{idp}$ with the following properties:

- They are double protected for β_0 for OR and M models.
- If both models are correct, they have asymptotic variance equal to the smallest asymptotic variance of all estimators $\hat{\beta}_{\tau ipw}$.
- They lie in the range of β_0 .

- Under model M, they are more efficient than $\hat{\beta}_{ipw}$.

Longitudinal Data : for $1 \leq i \leq n$

$$L_{0i}, A_{0i}, L_{1i}, \dots, L_{ki}, \dots, L_{si}, A_{si}, L_{s+1i}, \quad \text{iid,}$$

where

- $L_{ki} \in \mathbb{R}^{m_k}$ $0 \leq k \leq s$ pre-treatment variables.
- A_{ki} $0 \leq k \leq s$ treatment variables.
- $Y_i = \varphi(L_{0i}, L_{1i}, \dots, L_{s+1i})$ outcome of interest.

Causal Analysis.

Regime g

- $g = (g_1, g_2 \dots g_s)$.
- $g_k(\ell_0, \ell_1, \dots, \ell_k) = \text{treatment at time } k$.
- $G = \{g_x : x \in \mathcal{X}\}$.

Contrafactual variables:

We have $(L_0, A_0, L_1 \dots A_s L_{s+1})$ (Factual variables).

Contrafactual variables: given a regime g

$L_{k,g}$ = answer at time k which would be observed in the world where everybody is forced to follow the regime g .

Consistency assumption:

$$A_k = g_k(L_0, L_1, \dots, L_k) \quad \text{then} \quad L_{k+1,g} = L_{k+1}. \quad (14)$$

In causal Analysis we try to identify and estimate, from factual variables and longitudinal data respectively, causal parameters like $E[Y_g]$.

Relation with missing data and example:

- $s = 0$
- L_0, A_0, Y where $A_0 = 1$ (take the drug) or $A_0 = 0$ (don't take the drug)
- $g = 1$, ie: g = every body takes the drug, so $g(L_0) \equiv 1$ (static regimen.)
- $E[Y_g]$.
- if $A_0 = 1 = g(L_0)$ then $Y_g = Y$.

So, if we assume NUC (no unmeasured confounders - equivalent to MAR), this is a missing at random problem.

Marginal structural mean model

- $L_{0i} A_{0i} L_{1i} \dots L_{ki} \dots L_{si} A_{si} L_{s+1i},$ iid.
- $G = \{g_x : x \in \mathcal{X}\}.$

$$E [Y_{g_x} | Z] = h (x, Z; \beta_0) \quad x \in \mathcal{X}, \quad (15)$$

- $\beta_0 \in R^{p \times 1}$ is unknown, Z subset of components of L_0 , $h (\cdot, \cdot, \cdot)$ known smooth function.

- Murphy SA, van der Laan MJ, Robins JM, CPPRG (2001) proposed estimators for β_0 in marginal structural mean models with the same properties that $\hat{\beta}_{dp}(\hat{\eta}, \hat{\gamma})$.
- Lately M.Sued, A. Rotnitzky and myself have improved those estimators following the same spirit as the one used to construct $\hat{\beta}_{idp}(\hat{\eta}, \hat{\gamma})$.

References

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